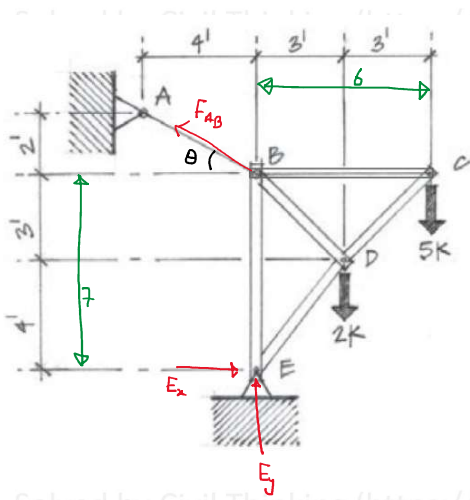
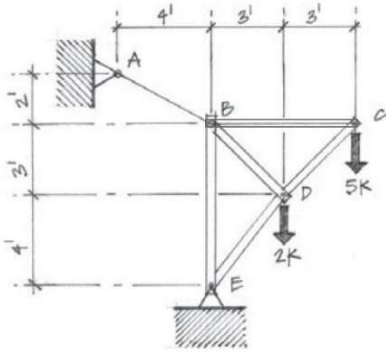


Find Truss Member Forces using Method of Joints

Using the method of joints, determine the force in each member of the truss shown in the drawings below. Summarize the results on a force summation diagram, and indicate whether each member is in tension or compression



$$\sum M_E = 0 :$$

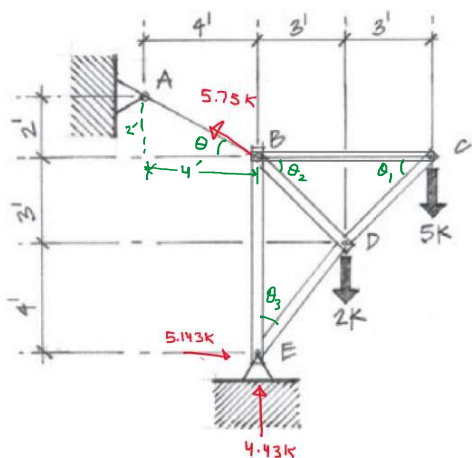
$$(5K \times 6) - (F_{AB} \cos \theta \times 7) + (2K \times 3) = 0 \Rightarrow F_{AB} = 5.75 K$$

$$+\uparrow \sum F_y = 0 :$$

$$E_y + F_{AB} \sin \theta - 2K - 5K = 0 \Rightarrow E_y = 4.43 K$$

$$+\rightarrow \sum F_x = 0 :$$

$$E_x - F_{AB} \cos \theta = 0 \Rightarrow E_x = 5.75K \times \frac{2}{\sqrt{5}} = 5.143 K \Rightarrow E_x = 5.143 K$$



$$\theta_1 = \tan^{-1} \frac{3}{3} = 45^\circ$$

$$\theta = \tan^{-1} \frac{2}{4} = 26.565^\circ$$

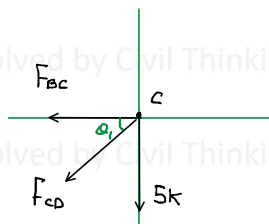
$$\theta_2 = \tan^{-1} \frac{3}{3} = 45^\circ$$

$$\theta_3 = \tan^{-1} \frac{3}{4} = 36.87^\circ$$

Joint C :

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Joint C:



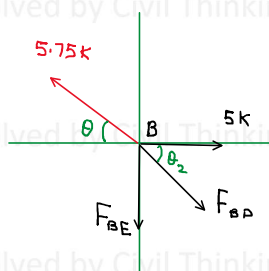
$$+\uparrow \sum F_y = 0:$$

$$-5k - F_{CD} \sin \theta_1 = 0 \Rightarrow F_{CD} = -5\sqrt{2}k$$

$$+\rightarrow \sum F_x = 0:$$

$$-F_{BC} - F_{CD} \cos 45^\circ = 0 \Rightarrow F_{BC} = 5k$$

Joint B:



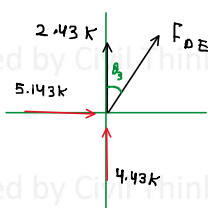
$$+\rightarrow \sum F_x = 0:$$

$$F_{BD} \cos \theta_2 + 5k - 5.75k \cos \theta = 0 \Rightarrow F_{BD} = 0.202k$$

$$+\uparrow \sum F_y = 0:$$

$$5.75k \sin \theta - F_{BE} - F_{BD} \sin \theta_2 = 0 \Rightarrow F_{BE} = 2.43k$$

Joint E:



$$+\rightarrow \sum F_x = 0:$$

$$F_{DE} \sin \theta_3 + 5.143k = 0 \Rightarrow F_{DE} = -8.57k$$

Class check:

$$+\uparrow \sum F_y = 0:$$

$$4.43k + 2.43k + F_{DE} \cos \theta_3 = 0 \Rightarrow F_{DE} = -8.57k$$

Both $\sum F_x = 0$ and $\sum F_y = 0$ provided same answer to $F_{DE} \Rightarrow$ Passed

Summary:

Summary:Solved by Civil Thinking (<https://civilthinking.com>)Solved by Civil Thinking (<https://civilthinking.com>)Solved by Civil Thinking (<https://civilthinking.com>)

$$F_{CD} = 5\sqrt{2} \text{ K (C)}$$

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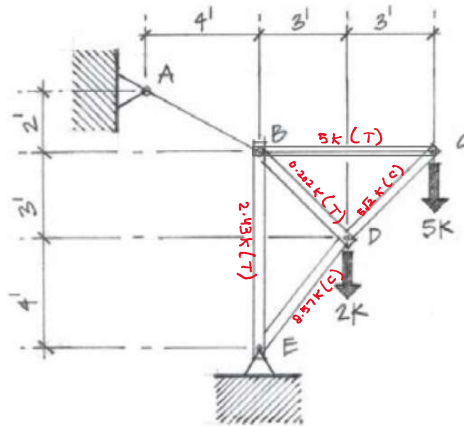
$$F_{BC} = 5 \text{ K (T)}$$

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$$F_{BD} = 0.202 \text{ K (T)}$$

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$$F_{BE} = 2.43 \text{ K (T)}$$

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